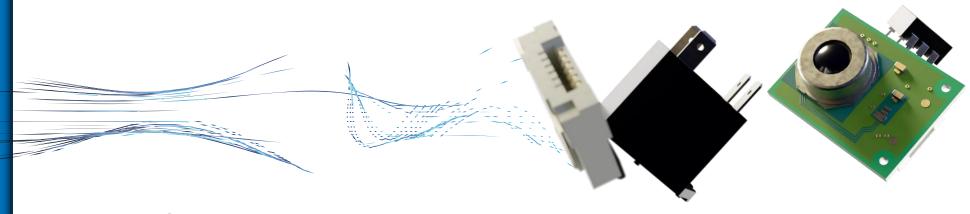
Electronic Components Europe



GABRIELE FULCO

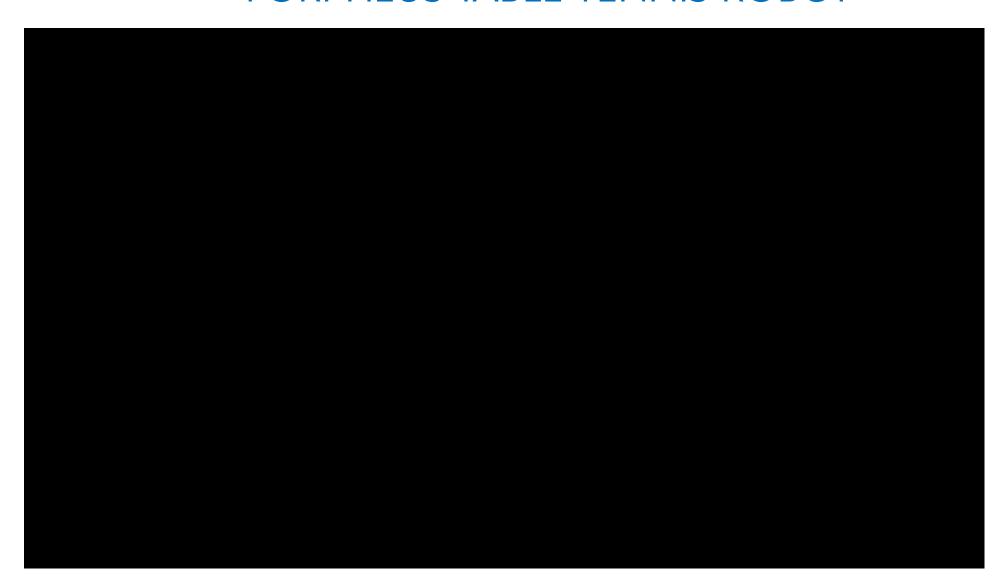
TSM N&S

**ROBOTICS** 

**OMRON SENSORS** 



# FORPHEUS TABLE TENNIS ROBOT







# Cooperate Overview

Omron has been pursuing innovation driven by social needs for creating a better society. Omron's four main businesses are Industrial Automation, Device & Module Solutions, Social Systems, Solutions and Service, and Healthcare.

### **Healthcare Business**

Providing a comprehensive lineup of healthcare products for home and hospital use (e.g. digital blood pressure monitors, thermometers)

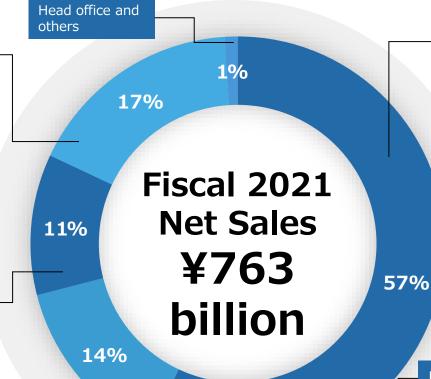


# Social systems, Solutions and service Business

Offering social infrastructure systems for a safer, more comfortable society (e.g. automated ticket gates and vending machines, solar power conditioners, storage batter systems)







### Industrial Automation Business

OMRON's mainstay business; innovating global manufacturing through factory automation (e.g. sensors, controllers, robots)



### Device & Module Solutions Business

Providing the market with sophisticated components that create seamless relationships between people and machines (e.g. relays, switches)





# DMS **SENSORS** LINE UP

Digital signage Market research Vending machines Smart appliances **Building automation** Security

Register / pos

Communication robots

Security systems **Building automation** Energy management Human detection

### TOF sensor

Factory automation Logistics and conveyance Autonomous mobile robots (AMR) Automated guided vehicles (AGV) Patient monitoring and observation Automatic doors/elevators

### Touch sensor

Lights Bevators. Vending machines Water faucets

Combustion control Fuel cell Water heater

Boller **Bectronics** 

Projector

PC, server Other AV electronics

### Pressure sensor

Altitude Water depth

Atmosphere

**Building automation** 

Smartphone/Tablet

Pedometer

Drone

Watch/Wearable indoor navigation



**Building automation** Room monitoring Office environment monitoring Weather change alert

### **D7S**

Earthquake detection Preventing secondary damage Determining damage Disaster map creation Prevention



### Tilt sensor

Vending machines Cash machines Alarm systems Fork lifts Cranes, material handling equipment

Standalone oil heaters



**PMS** 

IP camera

AGN

Factory automation

Service robots

Building automation

Encoders



Industrial automation

Drives control

Water meters

Energy

Automation system

Non-contact switch



Printers, copiers, scanners

Digital image

Piotees

Mouse

Post machines

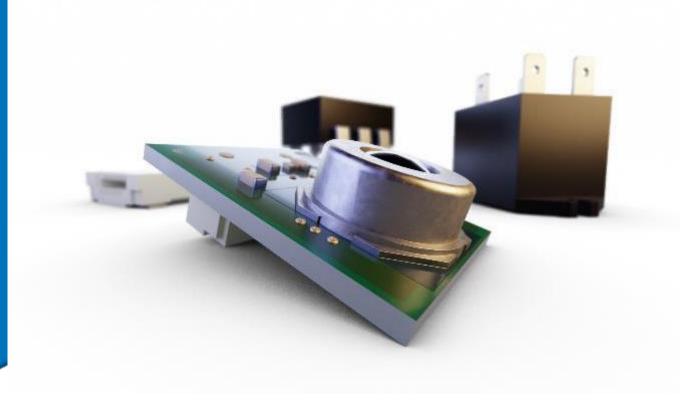
Ticket machines





Robot cleaners Coffee machines Vending machines





# **AGENDA**

1.B5L 3D TOF SENSOR

2.B5T HVC HUMAN VISION COMPONENT

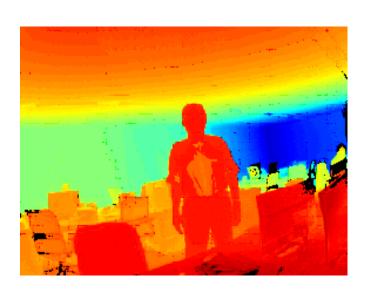
**3.OKAO FACE RECOGNITION V9** 

**4.D6T THERMAL SENSOR** 

5.B5W-LB/DB LCR/LDR SENSORS



# 3D TOF Sensor Module B5L series



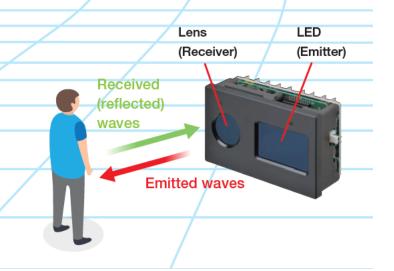




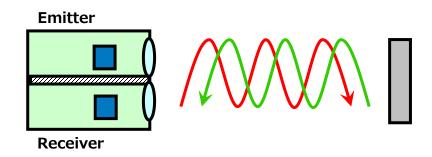
# WHAT IS A TOF SENSOR?

### What is a TOF Sensor?

A TOF (Time of Flight) sensor uses the flight time of light to measure distances to objects. As well as being able to turn captured images into 3D images, it can also measure at a speed of 20 frames per second, allowing it to track the movement of objects three-dimensionally.

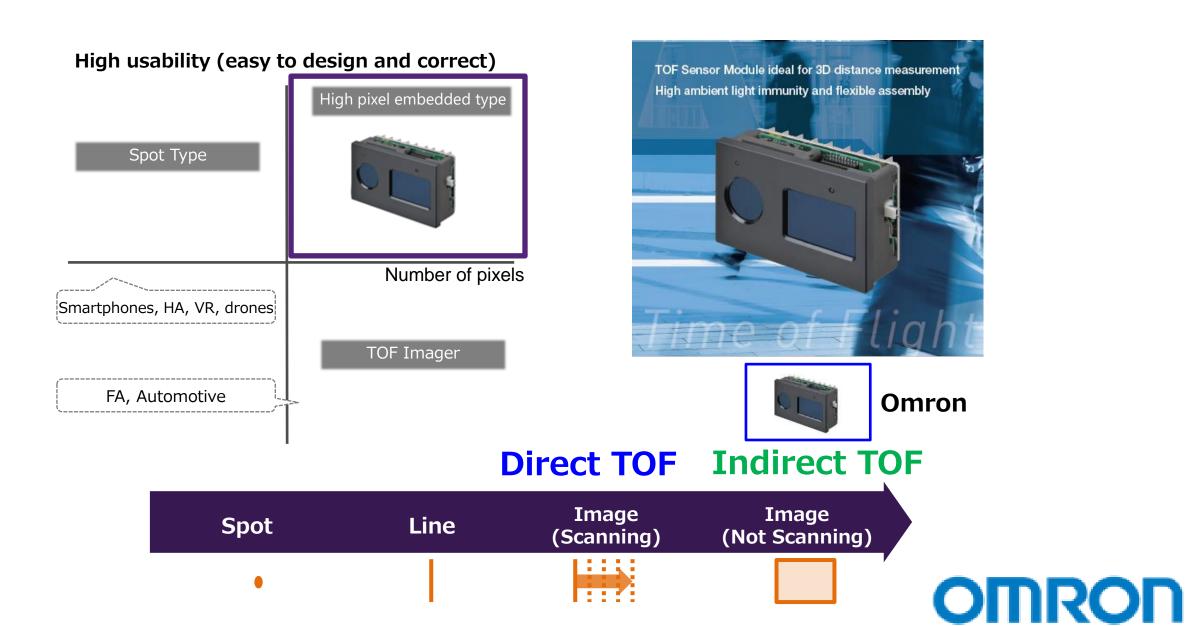


The principle of OMRON products is "Indirect TOF"





# DIFFERENT CATEGORIES OF TOF SENSOR



# **OUTPUT EXAMPLE**

BY COMBINING MULTIPLE DISTANCE INFORMATION, IT IS POSSIBLE TO RECOGNIZE A WIDE RANGE OF SURROUNDING ENVIRONMENTS.

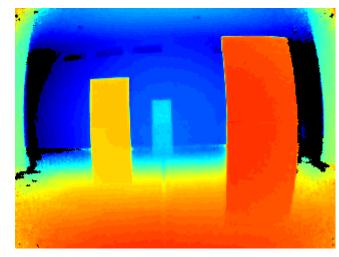
### **RGB Camera**

Outputs RGB color shades for each pixel



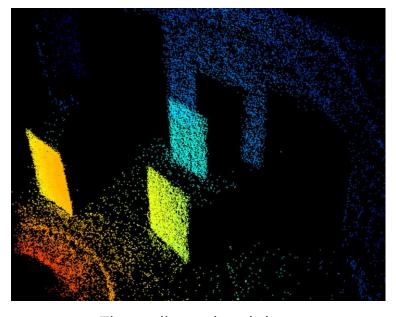
### **3D TOF Sensor**

Outputs the distance value for each pixel



Display distance in color Near: Red ~ Far: Blue

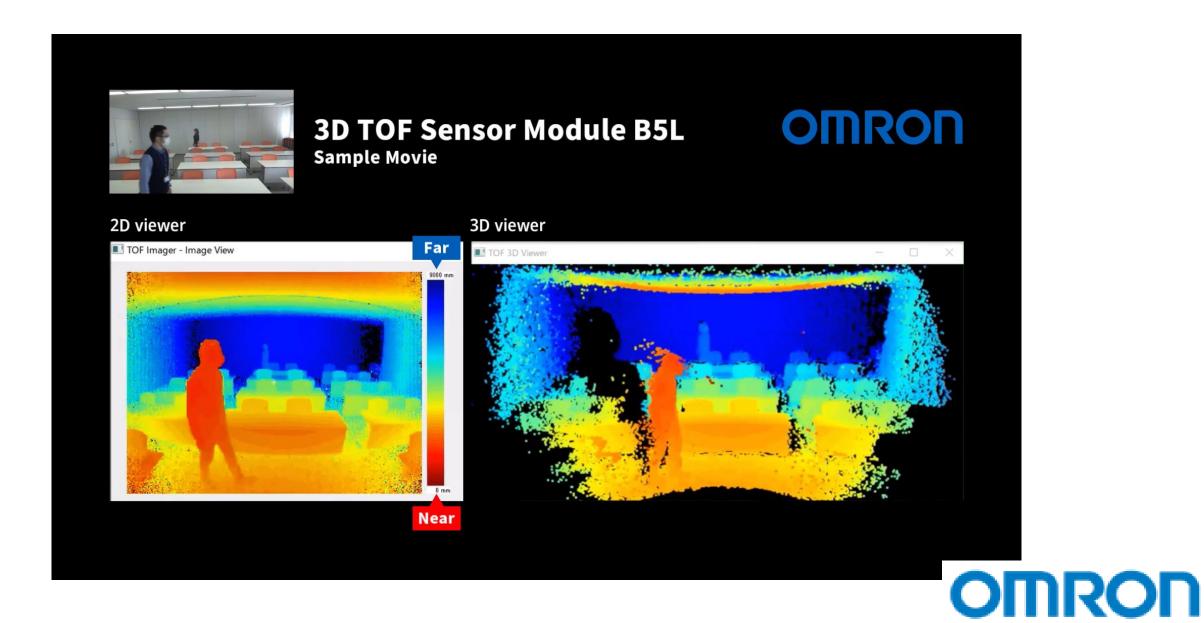
Output X, Y, Z coordinates for each pixel



Three-dimensional data



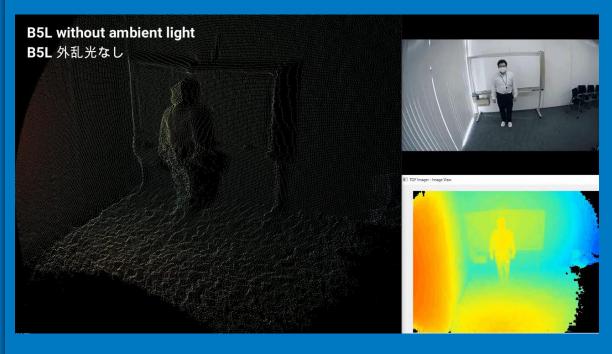
# **DEMONSTRATION VIDEO**



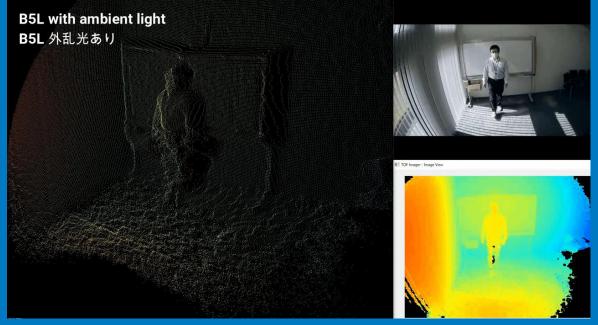
# FEATURES: INTERFERING LIGHT IMMUNITY

OUTPUT EVEN IN AN ENVIRONMENT WHERE AMBIENT LIGHT IS GENERATED

### Without ambient



### With ambient



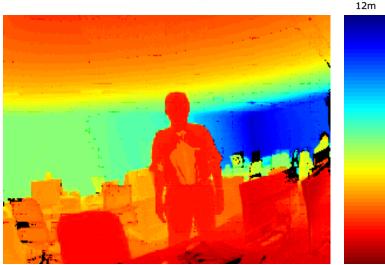
Without ambient : <a href="https://youtu.be/cUphHe2kkVc">https://youtu.be/cUphHe2kkVc</a>

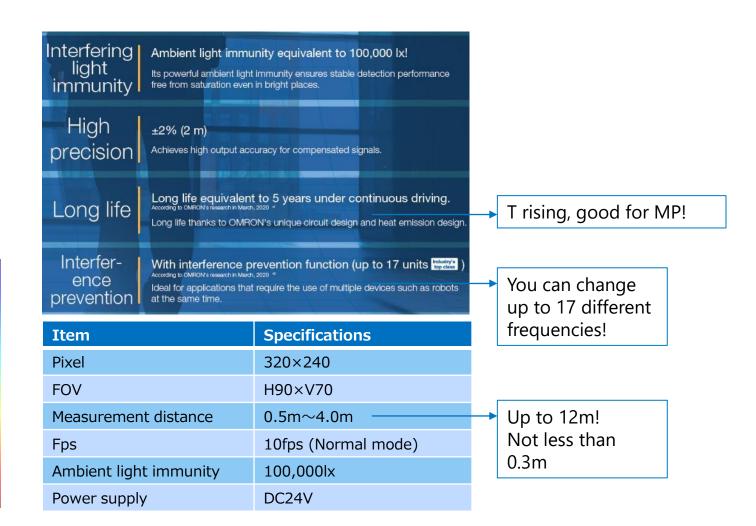
With ambient: <a href="https://youtu.be/bjGOGxrvDfo">https://youtu.be/bjGOGxrvDfo</a>



# **PRODUCT FEATURES & BENEFITS**









# PRODUCT TECHNOLOGY

### AMBIENT LIGHT IMMUNITY EQUIVALENT TO 100,000LUX

### Test Data

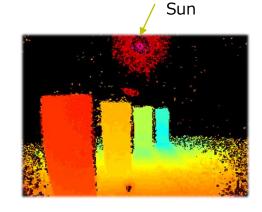


### Optical design technology

- \*Lens design that corresponds to the wavelength of the emitter LEDs
- \*Arrangement of emitters and receivers minimizing the effect of suspended particles of dust-
- \*Optical simulation technology

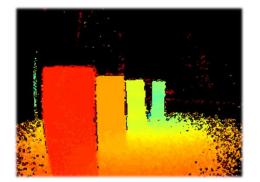
### ■Back light





■Normal light

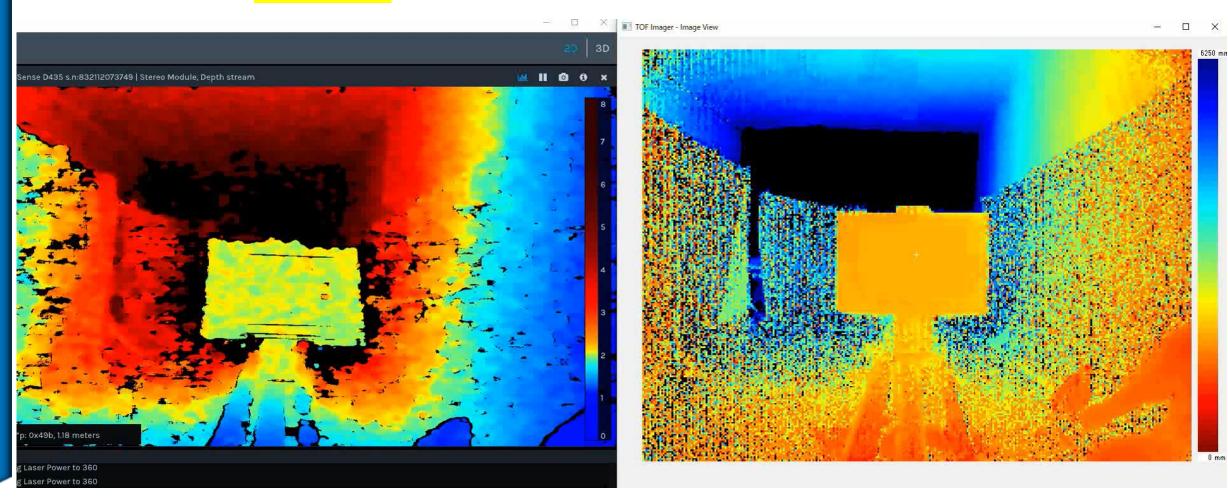






# **COMPARISON VIDEO**

COMPARISON TEST WITH ONLY 1000LUX LIGHT!!



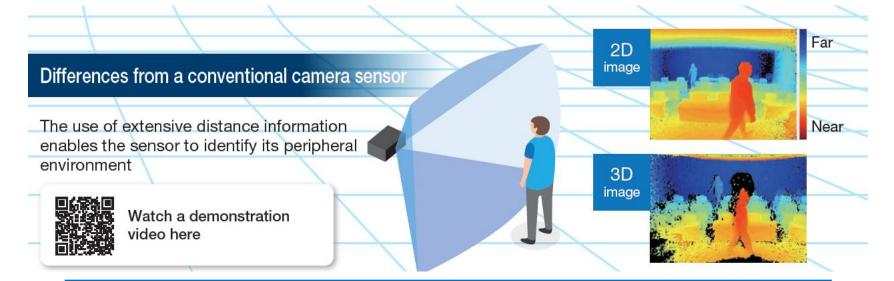


# **B5L SUMMARY VIDEO**



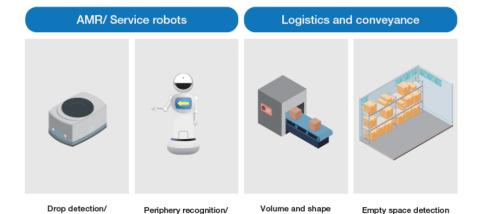


# **MAIN APPLICATIONS**



Peripheral recognition application, volume / shape recognition, lead wire tracking / behavior grasp

Technology that is expected to expand the market as the "eye" of equipment

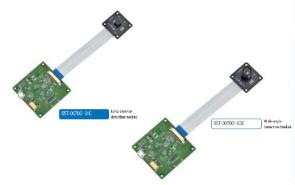


Human recognition

Environment recognition



Human
Vision
Components





OMRON's Image Sensing technology is the answer.





# **Market Trend**



### In the near future

# Machines adapt to humans

Machines adjust their functions and performance to the user's ability level/gender/age

# Sensing Control core competence

In the past

Humans adapt to machines

### Facial Image Sensing "OKAO Vision"

Micro machining Micro photonics Knowledge Information Control Technology



# **OKAO VISION SOFTWARE**

### **Digital camera/DVC**



- Face Auto Focus
- Face Auto Red-Eye Correction
- Face Auto Framing etc.



# Home Electronics, Printers etc.

- Individual Recognition
- Facial brightnessAdjustment
- · Beautiful Skin
- Red-Eye Reduction etc.









- Face Auto Focus
- Face Auto Iris
- Individual Recognition
- · Face Editing Tools etc.
- **Mobile Devices**

- Face Detection
- Attribute Estimation
- Smile Degree Estimation etc.



**Products for Public works** 



# What is Human Vision Components?

# **Embedded device integrating OKAO technology on a board with camera and CPU**

**OKAO** 

Circuit Design Technology

Face Recognition algorithm ideal for the hardware





Circuit design ideal for the algorithm



### **Human Vision Components (HVC)**

### **Easy**

Camera and processor are included, the customer can use the image it easy.

### Compact, but powerful

\* 45mm, but it can detect the human features up to 4 times per second.

### **Flexibility**

2 kinds camera type are available, the customer can select depends on the application.

### **Various functions**

10 image sensing functions are included in this small board.

### **Development support**

The evaluation software and sample code are available, contribute faster development leadtime.



# Which features does HVC-P2 include?

GDPR Friendly

### 10 image sensing functions included, which can be activated together







HVC is not storing full images, just only raw data

Impossible to re-produce full image

No privacy issue



# - Face Detection -

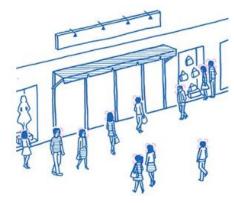
Detect with high accuracy and speed multiple faces of various size through the use of a unique algorithm

### **Features**

- Can detect faces in all 360 degrees roll angle.
- Can detect and track faces partially occluded.

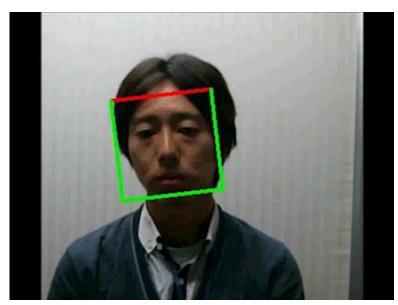


### **Application example**



Count number of visitor in the shopping mall or super market

Count number of visitor automatically, it can reduce labor costs



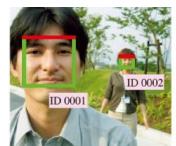


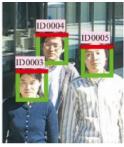
# - Face Recognition -

### Recognition can be done in various conditions

### **Features**

- Can recognize person with high accuracy under various conditions (face orientation, expressions, lighting conditions and skin tones).
- Can be used for face search or login features.
- Can be used for real time recognition in various devices.



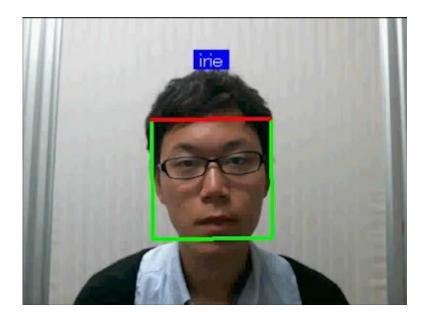


### **Application example**



- Access control
- Security gate

Limit access to restricted areas by recognizing people and improve security







# **PCN**

# OMRON

### **Modifications Notices**

**Human Image Sensing Technology** 

Issue Date February 1, 2022

No. 2022028AE(ON)

Firmware design changes for addition of functions of Human Vision Components HVC-P2 (model B5T) of Modification Notice.

### [ Effective Date ]

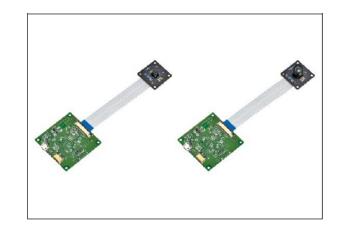
Effective as of our production in February 2022.

### [ Applicable Model ]

Model B5T-007001 series < Refer to the "[Details of applicable model]".>

### [ Reason for change ]

For upgrading to the new firmware with the addition of the commands for "1:1 verification" and "changing maximum number of registered people in Album" for face recognition.



### [ Details of applicable model ]

Models
B5T-007001-010
B5T-007001-010-H
B5T-007001-020
B5T-007001-020-H



# **CHANGES**

# Changes ]

### Before the change After the change

Image Sensing Functions

image censing ranctions				
Function	Output	Details		
Face Recognition	•Individual identificati on result	Displays either the registered User ID, or "non-registered" for non-registered individuals     Maximum number of users: 100     Maximum number of data per use: 10     Registration is done with the Product.     Matching degree (0 to 1000)     The result of the user with the highest matching degree is output.     A degree closer to 1000 indicates a higher likeliness of being that user.		

Image Sensing Functions

Function	Output	Details
Face Recognition	•Individual identification /verification result	<ul> <li>Identify whether the face image that was taken matches the registered user in the Album. As a result of identification, the ID for the user with the highest degree of matching is output. If the degree of matching with all users is less than the threshold, "Not registered" is output (1:n recognition = identification).</li> <li>It is possible to change to the mode that verify that whether the face image matches a specific user in all registered users (1:1 recognition = verification) by a command.</li> <li>Maximum number of User ID: 100 / Maximum number of data per User ID: 10 (Default value). This numbers can be changed to 500 User IDs x 2 data or 1000 User IDs x 1 data by commands.</li> <li>The image data that is taken with other than this product can not be registered.</li> </ul>
	•Score	Matching degree is 0 to 1000. The closer the degree is 1000, the closer the User ID is to the detected person.  Identification (1:n): The output is the result of user with the highest matching degree.  Verification (1:1): The output is the result of matching degree of specified ID's user.  The threshold value is can be set by command.



# - Human body detection -

### Detect human bodies that cannot be detected through face detection

### **Features**

- Can detect small, back-facing or backlit bodies
- Can detect squatting bodies.
- Can detect bodies in real time on embedded devices.
- Can be implemented in various equipment.

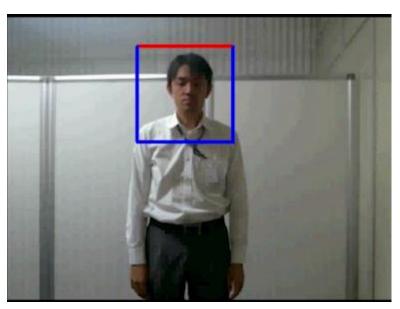
### **Application example**



- Air conditioner
- Lighting control
- Elevator

Detect people's location to optimize comfort and energy saving







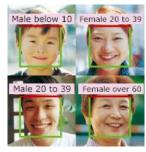
# - Age/Gender estimation -

### Estimate the gender and age from the facial image

### **Features**

- Can estimate the gender and age of a face with high estimation regardless of skin tones.
- Age and gender counting for customer analysis
- Can be used for real time estimation in various devices.



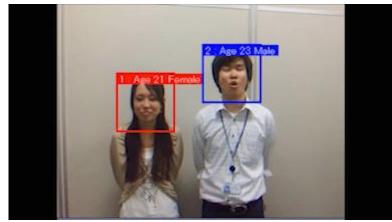


### **Application example**



- Digital signage
- Vending machine

Change advertisement based on user's age/gender, increase the appeal of products





# - Expression estimation -

### Estimate the facial expression from the facial image

### **Features**

- Can estimate 5 expressions (neutral, happiness, surprise, anger and sadness).
- Can estimate the expression degree based on positive expressions (happiness) and negative expressions (anger and sadness).



### **Application example**



- Communication robot
- Training tool

Enjoy a new lifestyle with robots that can identify and support people





# - Gaze/Blink estimation -

Can detect the position of the eyes and mouth with OMRON's model fitting technology and estimate the gaze direction and blink degree of the eyes.

### **Features**

- Can estimate the gaze direction on both horizontal and vertical axis.
- Can quantify the blink degree of the eyes.
- Can be used for real time estimation in various devices.

### **Application example**



- Digital signage
- Home appliance

Detect how long the people is looking at the screen and where is the most attractive for him/her







# - Face Direction Estimation -

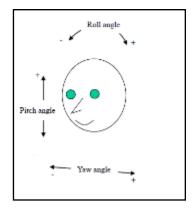
### Will estimate the direction of detected face

### **Features**

### **Output** is

- yaw angle
- pitch angle
- roll angle
- confidence level

# Right 30°



### **Application example**

- Digital Signage
- Retail
- Interactive Displays

	Yaw angle	Positive to the right (in degrees)
Face Direction Estimation	Pitch angle	Positive upwards (in degrees)
Pace Direction Estimation		Positive clockwise (in degrees)
	Degree of confidence	Confidence in the estimation result (0 to 1000), a higher value indicates a higher confidence



# - Hand Detection -

### **Detect hands in the image data**

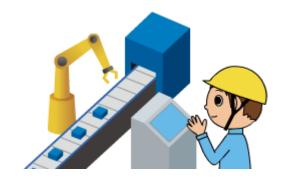
### **Features**

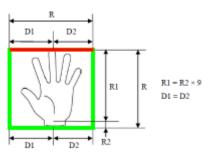
Only frontal hands (hands with the palm facing the camera) will be detected.

The result info will include the number of hands detected., position, size and degree of confidence

### **Application example**

- Harmful machinery
- Non-touch applications
- People with handicap





Function	Output	Details
	Number of detected objects	Maximum of 35 per object type
Human Body Detection, Hand Detection,	Position (center coordinates)	Coordinates on the screen from the top-left corner of the screen (in pixels)
Face Detection	Size	Pixel size on the input image
	Degree of confidence	Confidence in the detection result (0 to 1000), a higher value indicates a higher confidence



# Lineup and Main Specifications

Item	Long-distance type B5T-007001-010	Wide-angle type B5T-007001-020			
Appearance					
Horizontal detection range (angle of view)	Approximately 54 deg.	Approximately 94 deg.			
Vertical detection range (angle of view)	Approximately 41 deg.	Approximately 76 deg.			
Input resolution	1600x1200 pixel				
Output resolution	Selectable (no image output, 160 × 120 pixels, or 320 × 240 pixels)				
Dark location use	200 lx or above				
Supply voltage	DC 5 V ±0.5 V				
Consumption current	Below 0.4 A				
Power consumption	Below 2 W				
Operating temperature	0 to +50°C (no condensation or freezing)				
System	(1) UART 3.3 V (2) USB CDC-class device				



# Additional explanation of specification

### - Response time / distance



		HVC-P2 (50° type)		HVC-P2 (90° type)	
Functions	Distance	B5T-007001-010		B5T-007001-020	
		The smallest detection size	Response time (average)	The smallest detection size	Response time (average)
Face Detection	1.3m	1.3m 157pix	35ms	76pix	125ms
Face Recognition			59ms		149ms
Age / Gender Estimation			75ms		165ms
Expression Estimation			75ms		165ms
Human Body Detection	2.8m	183pix	35ms	88pix	110ms

	The	HVC-P2 (50° type)		HVC-P2 (90° type)	
Functions	smallest	D31 007001 010		B5T-007001-020	
	detection size	Distance	Response time (average)	Distance	Response time (average)
Face Detection	64pix	3m	140ms	1.5m	140ms
Human Body Detection	30pix	17m	970ms	8m	970ms

Even if 90deg, it is possible to estimate 6times/sec, it is enough for signage application.





# **Applications**















- Human Body Detection
- Face Detection
- Face Recognition
- Facial Pose and Gaze Estimation
- Facial Characteristics

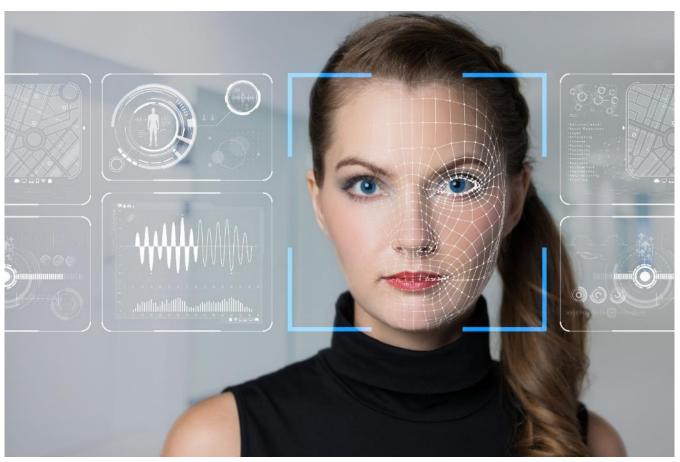




Image Sensing Technology **OKAO™ Vision** 

# Face Recognition V9.0

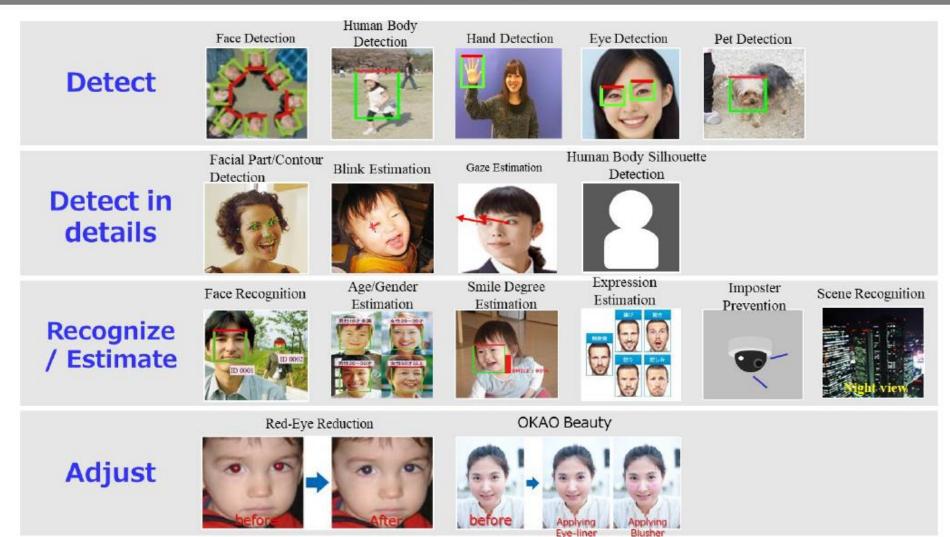


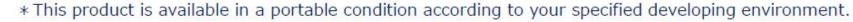




# **OKAO Software**

### It is a software library\* with image sensing functions for understanding humans.

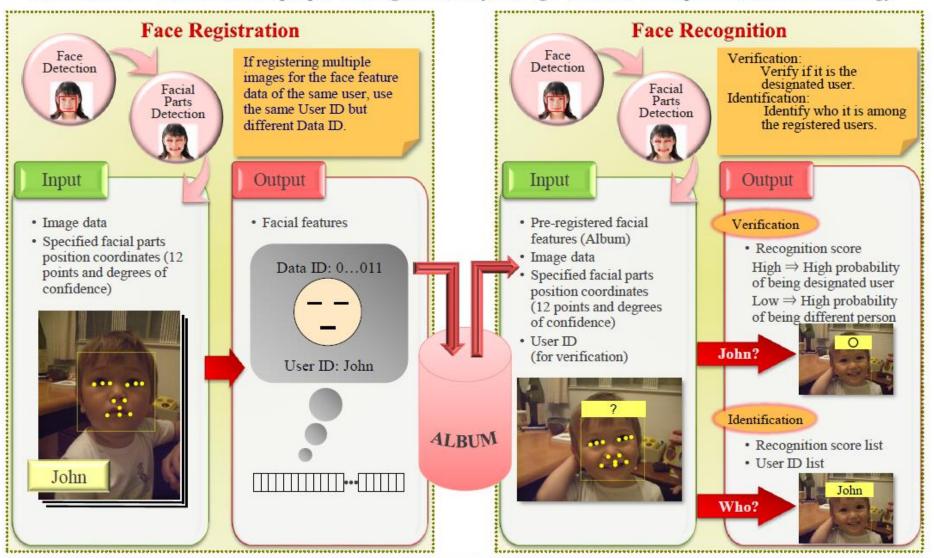






# **OKAO** Face Recognition

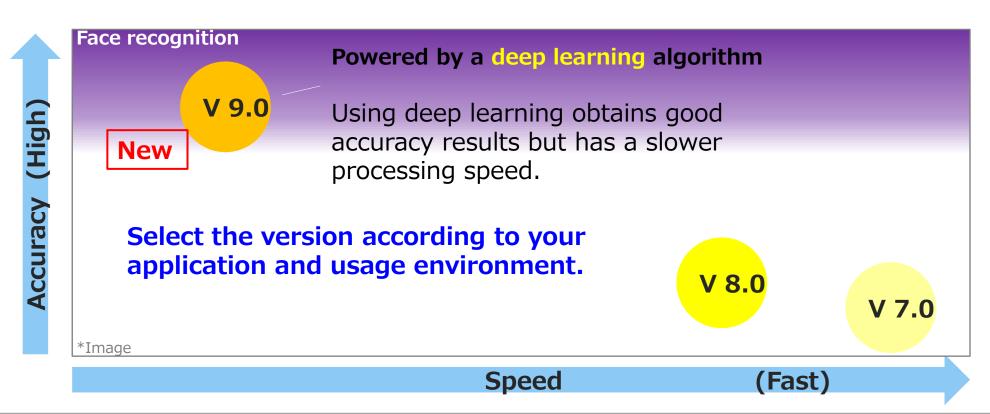
Differentiate a user from other people with high efficiency through OMRON's unique verification technology.



Face Recognition requires obtaining the facial parts position coordinates and degree of confidence information of a face to be used (Facial Parts Detection The facial parts position info requires obtaining the face position info to be used (Face Detection).



# Line-up and Main performance of each version







Face recognition

etc.

Expression estimation

# **OKAO** Face Recognition Features

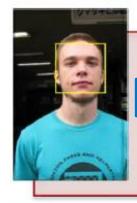


High accuracy rate for specified users due to verification and identification features



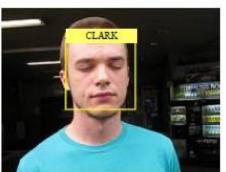






High accuracy in various
directions or lighting
conditions, regardless of facial
expressions or skin tones







Real time recognition available on various embedded devices

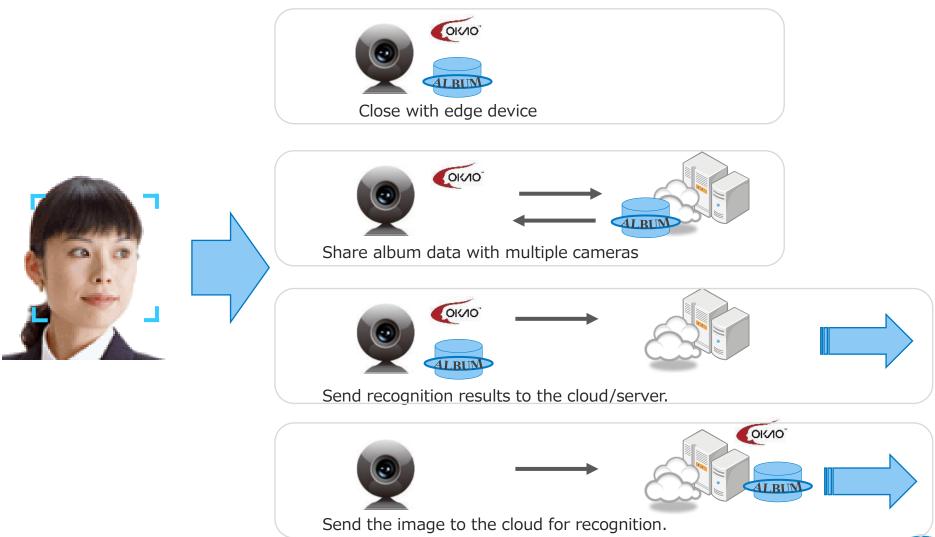






# System Design with Face Recognition

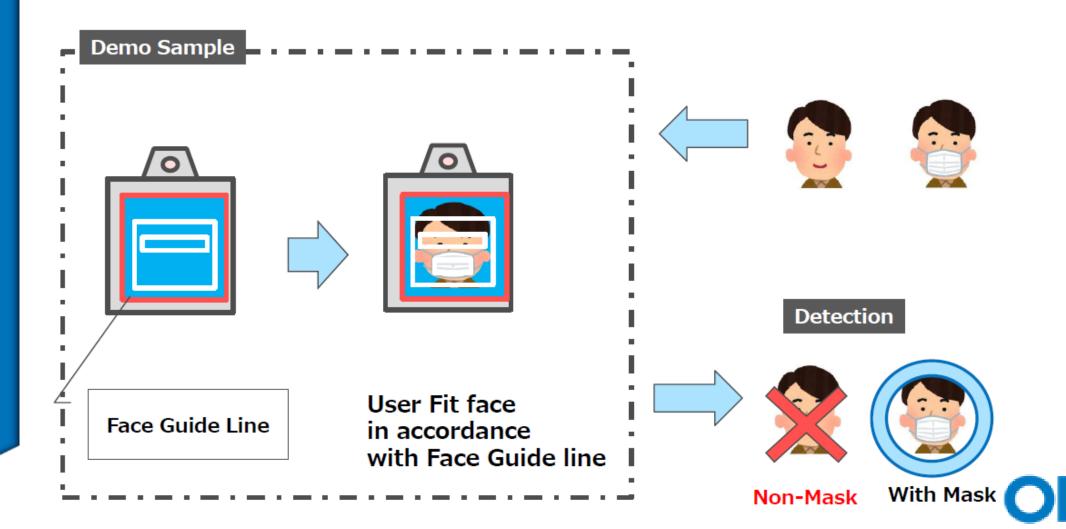
Configure the system according to your environment and purpose. If using OKAO, Applicable for own System Design.



## **Mask Detection**



Distinguish with Mask or Non-Mask





Non-Mask



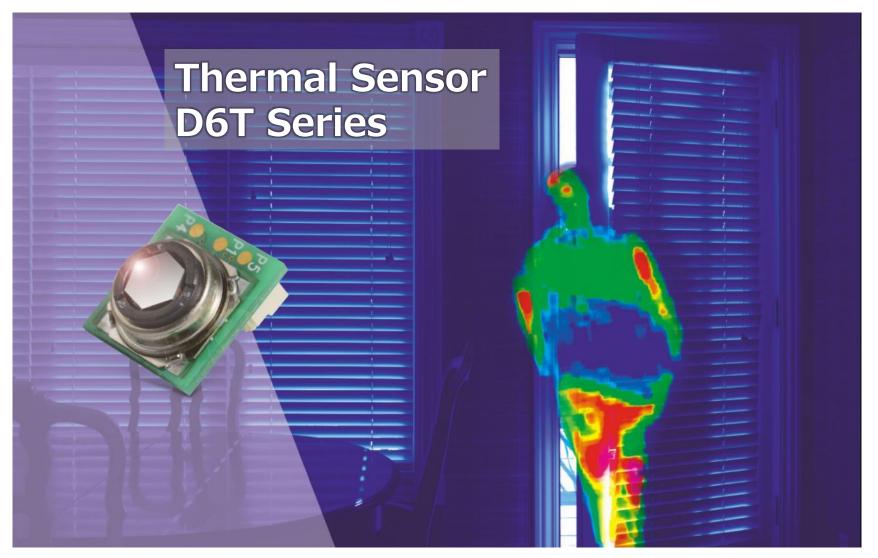
With Normal Mask



With Colorful Mask





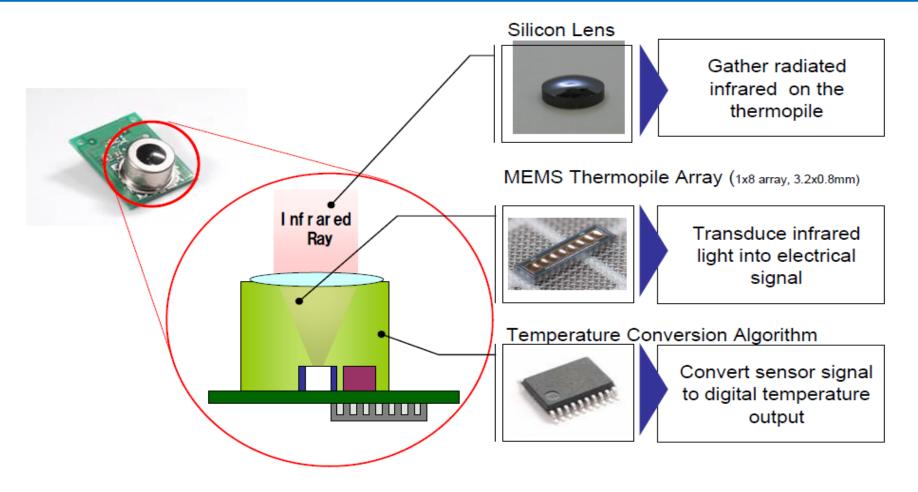






## Introduction of thermal sensor

## **D6T Operation principle**



Achieve High SNR and fast response speed by MEMS, IC and optical design



## How to use Data

## Thermal sensor



20.0	21.4	22.8	27.2
21.3	25.3	28.3	29.6
23.5	25.1	29.5	29.9
23.4	23.7	27.4	27.1

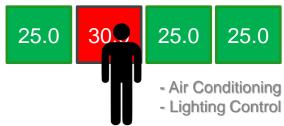
Output: Temperature(degC) of 16 places

# Customer's system



Using temperature information, convert it to the following information on customer's system.

## Human detection



The system judges that a human is present from the temperature difference.

## Object detection



- Refrigerator

The system judges that an object is present from the temperature difference.

# Temperature detection



- Machine in FA

The system can detect that a certain place is abnormal temperature.



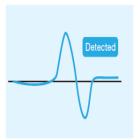
# Pyro sensor vs MEMS thermal sensor

Pyro-electric sensor relies on motion detection, while non-contact MEMS thermal sensor is able to detect the presence of stationary humans or objects.

MEMS thermal sensor (thermopile)

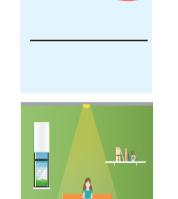
Output signal

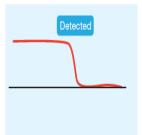
Converts temperature readings only when detecting "temperature changes in the ra Pyroelectric sensor energy" in its field of view. Output signal **Jndetected** 











Converts temperature readings by "continuously detecting the

temperature of radiant energy" in its field of view



Able to detect human (object) motion

Unable to detect stationary human (object) presence

Able to detect human (object) motion

Able to detect both stationary and motion state of humans (objects).



# Product Range

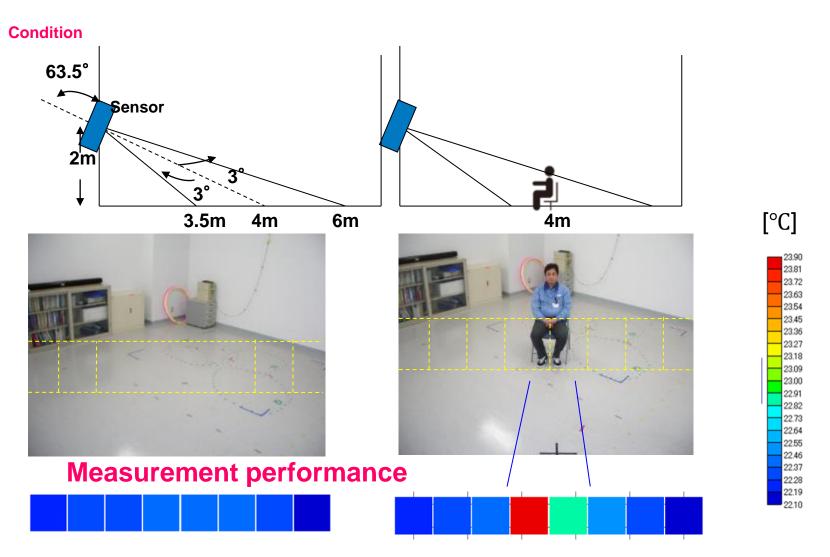




# IR MEMS 1 x 8 Array Sensor

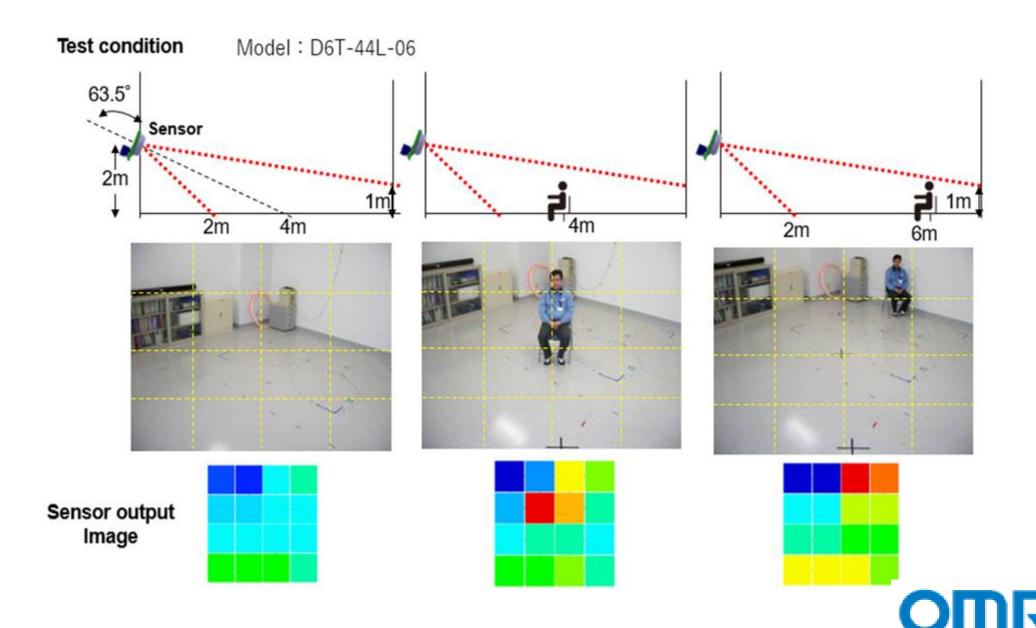
Accurate detection - Floor temperature and detect Human detection.

Even if there is no Human, Floor temperature can be measured correctly.





# IR MEMS 4 x 4 Array Sensor

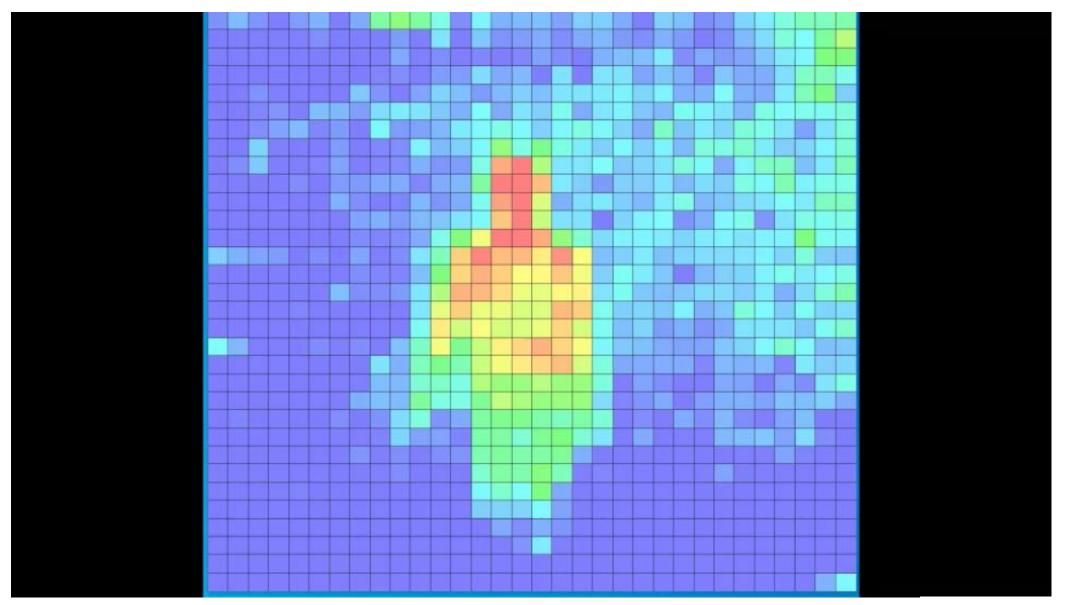


# High resolution temperature monitoring





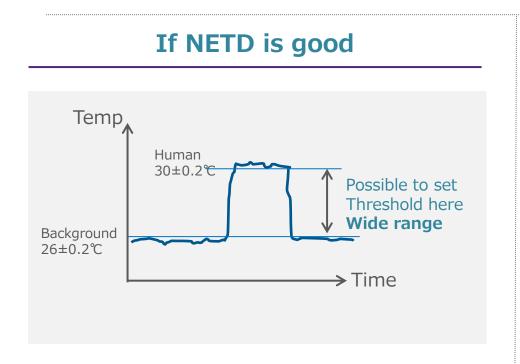
## Demo Movie 32x32

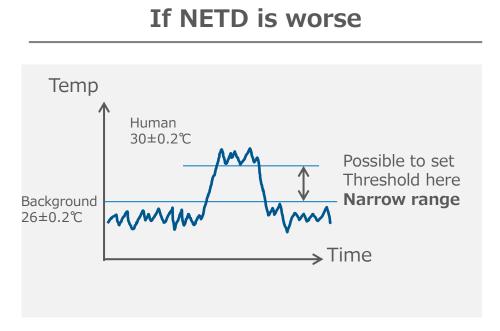




# D6T Advantage #1 – Noise Immunity (NETD)

- Human detection is judged based on **temperature difference**.
- Therefore, **NETD** is key for human detection.
- Omron IR sensor has World best class stability, based on self-manufactured low noise MEMS&ASIC.







# Omron advantage for human detection

- Human detection is judged based on temperature difference.
- Therefore, **NETD** is key for human detection.
- Omron IR sensor have good performance for NETD.

Chart: Comparison test

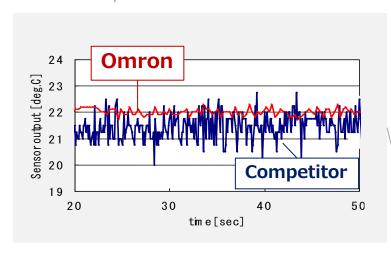


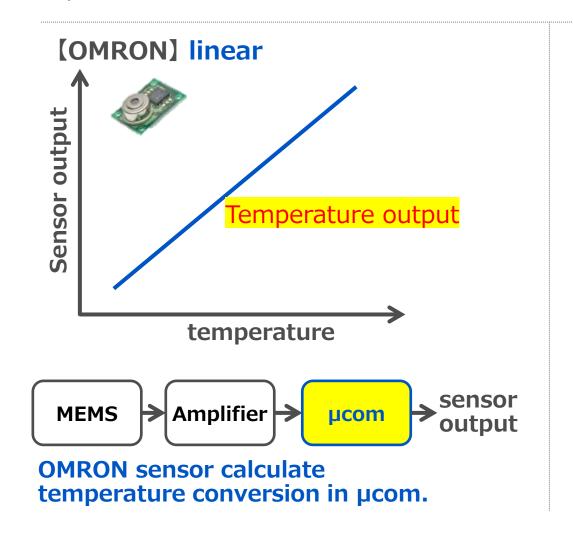
Chart: Specification comparison

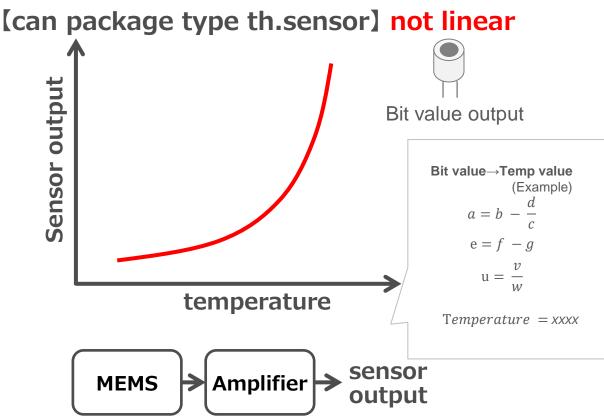
	Omron D6T-44L-06	Competitor A	Competitor B
Pixel number	4x4 (16pixel)	8x8 (64pixel)	8x8 (64pixel)
FOV (Field of view)	X : 44.2° Y : 45.7°	X : 48° Y : 48°	X:60° Y:60°
Object temp	5 to 50°C	-20 to 120°C	0 to 80°C
Operating temp	0 to 50°C	-20 to 85°C	0 to 80°C
Temp resolution (NETD)	<b>0.06</b> °C	0.18°C 2fps	Normal type: 0.26°C 10fpcs High spec type: 0.16°C 10fps
Object temp accuracy	±1.5°C	±2°C	±2.5°C
Consumption	3.5mA typ	2.4mA	4.5mA typ
Comm interface	12C	I2C	12C
Supply voltage	4.5 to 5.5V	4.5 to 5.5V	3 to 3.6V / 4.5 to 5.5V



# D6T Advantage #2 – Direct Temperature Output

• In the case of some competitors, customer need to do complicated calculation to get temperature conversion information from the thermal sensor.



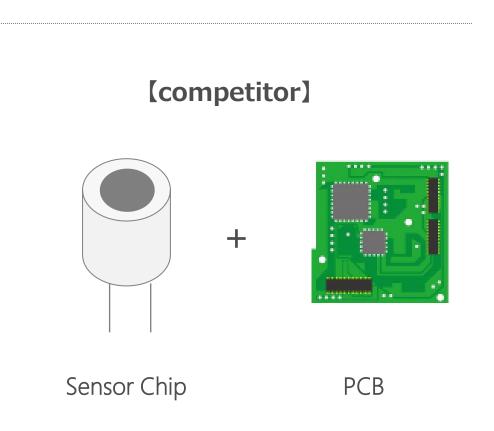




# D6T Advantages #3 – Complete Module

- With some competitors the customer has to design PCB/circuit which calculate sensor chip output data to temperature.
- Omron sells Sensor Module, while some competitors only Sensor element/chip.

# COMRON) Sensor Module

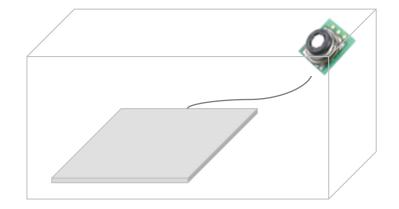




# D6T Advantages #4 – Easy Connection

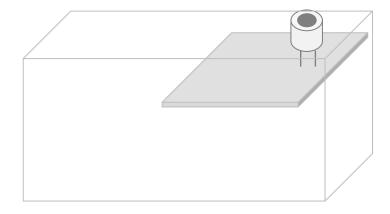
**OMRON D6T** 

Flexible position setting



Can package type thermal sensor

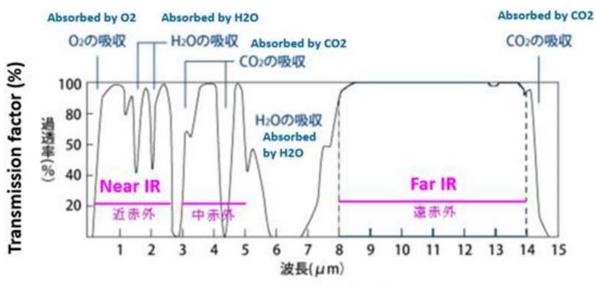
Not flexible





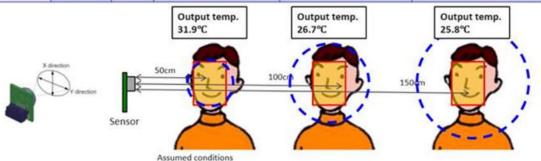
## Infrared Transmission

Atmosphere absorbtion only for Near IR



Wavelength (um)

Model	Direction	Distance tion FOV 50cm		Distance 100cm	Distance 150cm
			Detection area	Detection area	Detection area
DCT 44 03	X	26.5°	23.5cm	47.1cm	70.6cm
D6T-1A-02	Y	26.5°	23.5cm	47.1cm	70.6cm



✓ Face

Size: 15x20cm
Temperature: 35°C

✓ Background: 25°C

The focus is on the FOV!!



# **Applications**



## Temp monitoring

Home appliances



## **Human detection**

Building automation and robotics



## **Fever screening**

Gate access control



## Overheat detection

Transformer/Power cabinet



#### Recommendation



**8**. ...

A .

32x

## Recommendation



4.0



1x8

32x32



A

T.

### Recommendation



1x1



1



4X4

The second

32x32

### Recommendation



1x1



1x8



4x4



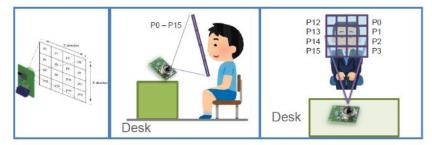
32x32



## D6T 1x1, 1x8, 4x4 + Sample Codes

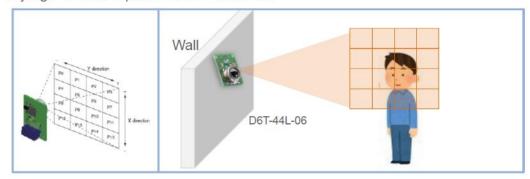
We don't have "D6T 4x4 with algorithm" but we can propose "D6T 4x4 + sample code for human detection". We can propose the sample code for human detection (Sample code should be implemented in customer's MCU).

This sample code can uses a D6T(4x4) installed on a desk to judge whether a person is on a seat or not.



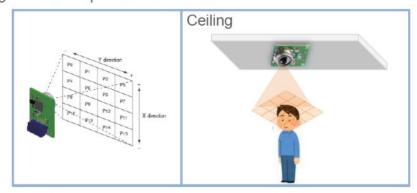
- Install D6T on the desk
- Install D6T so that the human face is within the field of view of D6T.

This sample code can uses a D6T(4x4) installed on wall to judge whether a person is in room or not.



- Install D6T on the wall
- Install D6T so that the human face is within the field of view of D6T.

This sample code can uses a D6T(4x4) installed on ceiling to judge whether a person is in room or not.



- Install D6T on the Ceiling
- Install D6T so that the human face is within the field of view of D6T.



## **B5W-LB** series

# Light Convergent Reflective Sensor (LCR)









## **Product Overview**

## **Sensing Stability**

Sensing capability of the product is **unaffected by** surface color, material, or reflectiveness.

## High Performance

Sensor is capable of detecting any object from black opaque to transparent.

# **Sensing Principle** Sensing **Spherical** lens LED **Detector**

# Glossy marble Kodak White Marble Black Glossy marble Kodak Wht(90%) Kodak Blk(3%) Transparent Capable of detecting black, white, and transparent objects

**Sensing Distance Characteristics** 

Technology

**Optical Lens Design** 

EMC Company

## **Product Features & Benefits**

## **Features**

Sensing distance between works in LCR sensors is smaller than that of general reflective sensors.

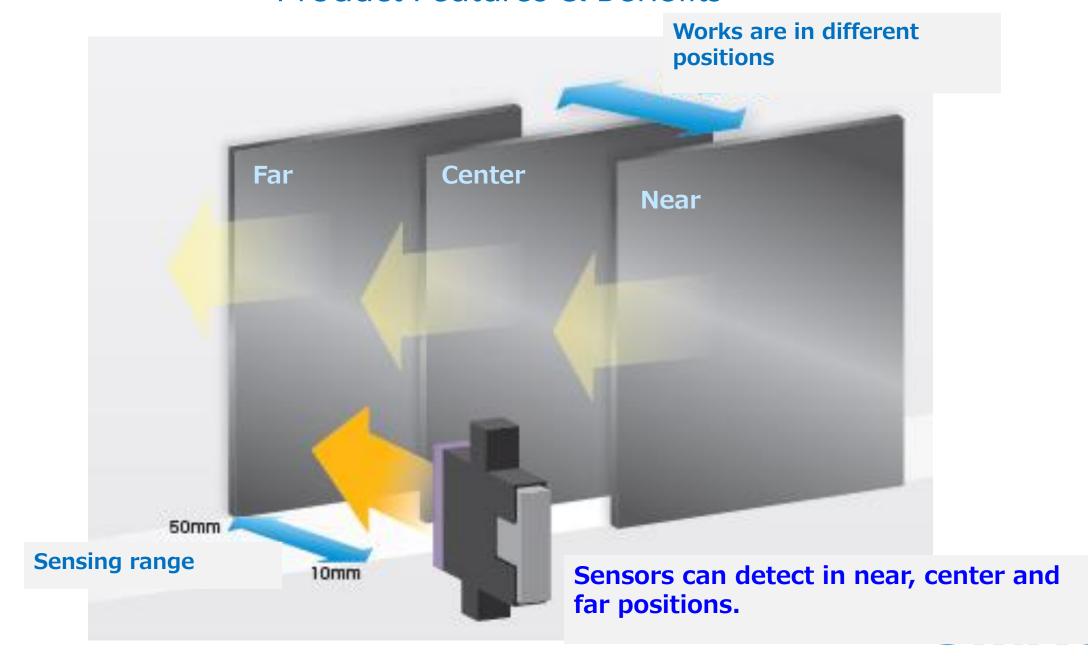
## **Benefits**

Robust to colors

LCR sensors have stable sensing performance to various colors of works and can contribute more added value in machines.

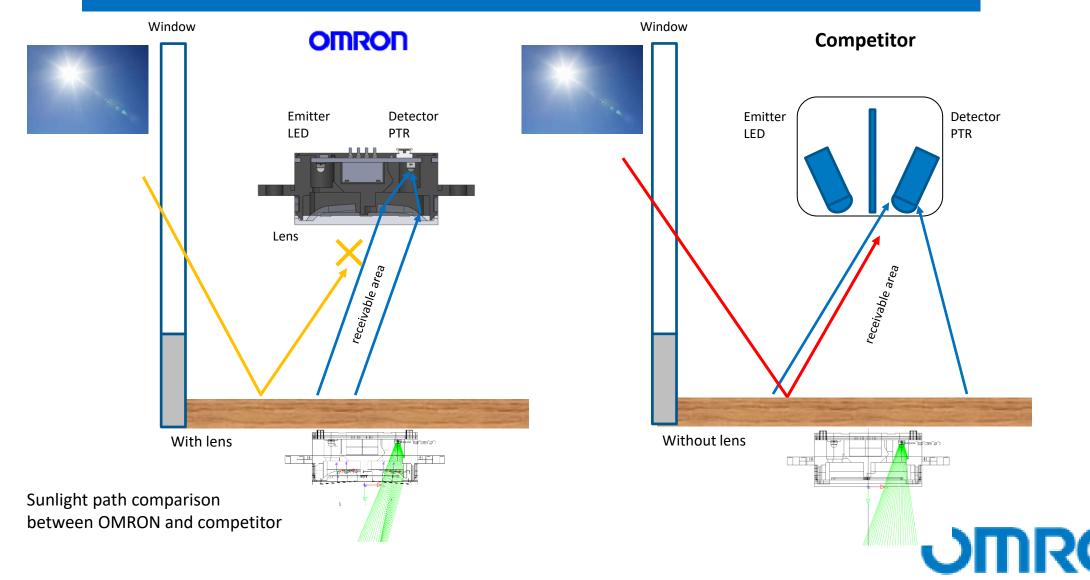
## Capable of sensing workpieces of various colors over a wide sensing range Sensing distance (mm) OFF OFF 70 50 50 40 40 30 30 -ON 20 -20 10 -10 Common **OMRON** Wider sensing range reflective B5W-LB2 sensors

## **Product Features & Benefits**



# Robustness against sunlight

OMRON's original optical technology enables the limited receivable area, it contributes to reduce the influence of sunlight disturbance.



## **Product Overview**

# Reliable Detection of Shiny, Black or Transparent objects

Light Convergent Reflective sensor for embedding in 24 VDC equipment



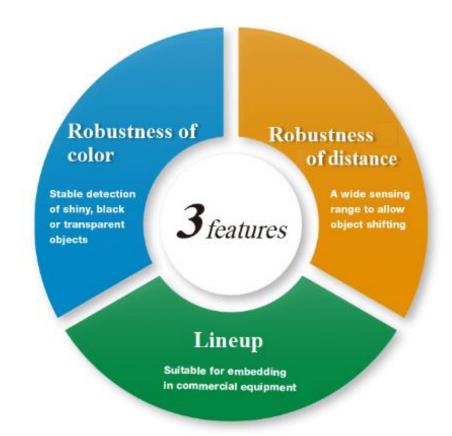
B5W-LB2□

Sensing distance 10 to 55 mm



B5W-LB1

Sensing distance 2 to 10 mm



	B5W-LB11series		B5W-LB2		21 series
Output method	Digital	output	Digital output		Analog output
Figure	Super miniature type		Miniature type		Miniature type
Sensing distance (White paper)	2 to 10 mm		10 to 55 mm		10 to 55 mm
Supply voltage	24 VDC +/- 10%		24 VDC +/- 10%		5 VDC +/- 10%
Output configuration	Light ON	Dark ON	Light ON	Dark ON	-

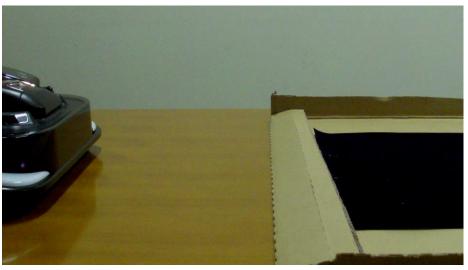
# Not Only Robot Cleaners!

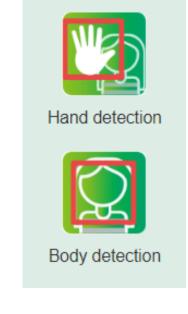
OMRON's sensor can detect steps correctly, less influence of the color and material.

## **OMRON**

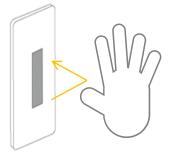


## Competitor





Non-contact switch



Not only robot cleaners!

Can be used in ROBOTICS for hand/body/objects detection



# New Type with Indicator



## Feature;

- The indicator lights up at the same time as the output transistor operation
- Users can understand when sensors can detect sensing objects by seeing the indicator.
- The same as B5W-LB1112-1 except for the indicator

Model type description; B5W-LB1114-1

Launch; Oct. 1st, 2020



When no objects,

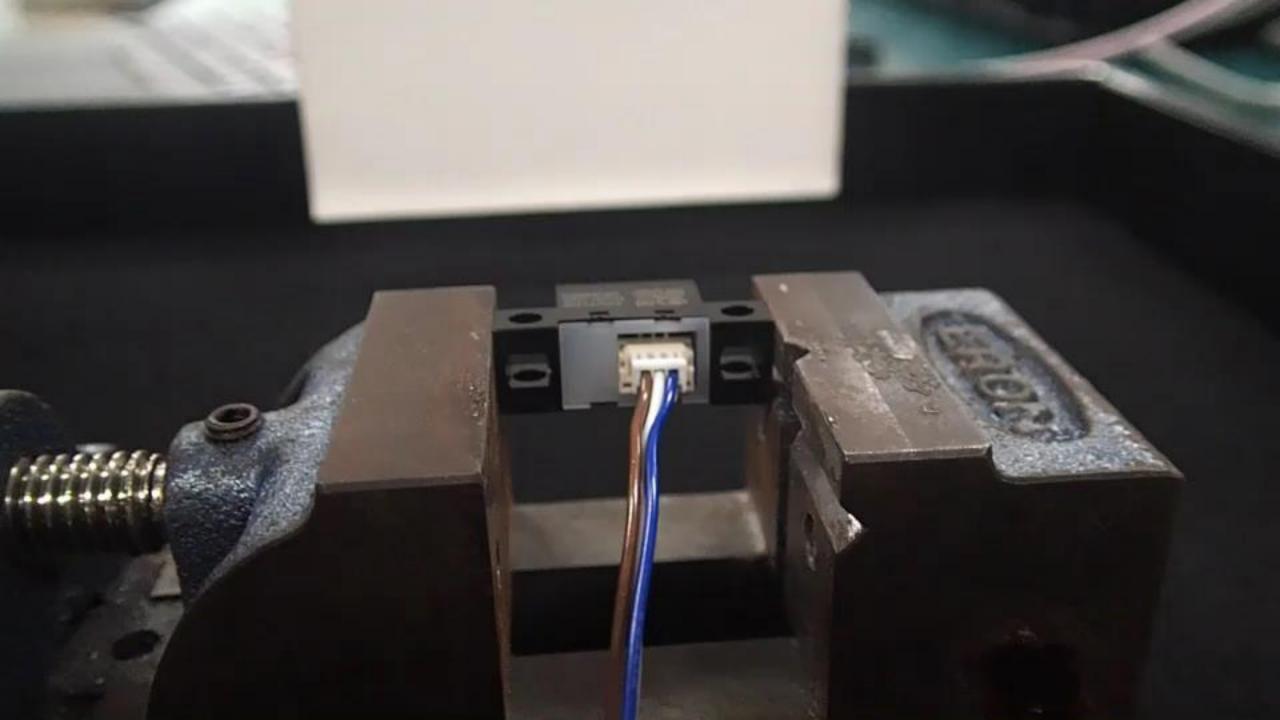
the indicator does not lights up.





<Indicator operation>
When detecting objects,
the indicator lights up.





B5W-DB series
Light Diffuse Reflective Sensor (LDR)



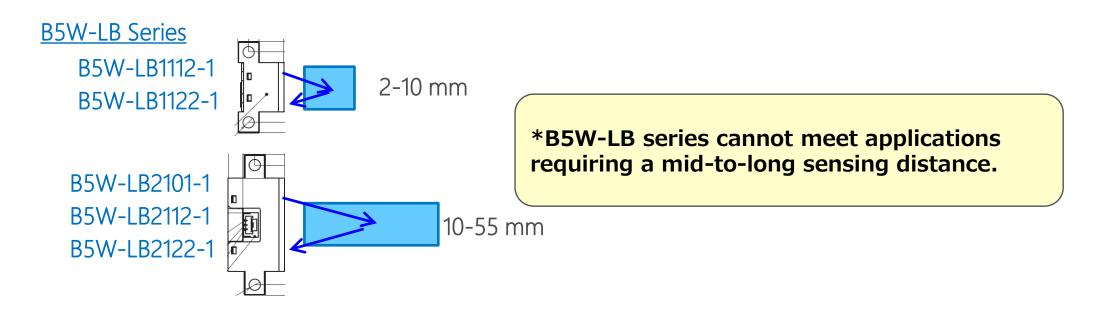


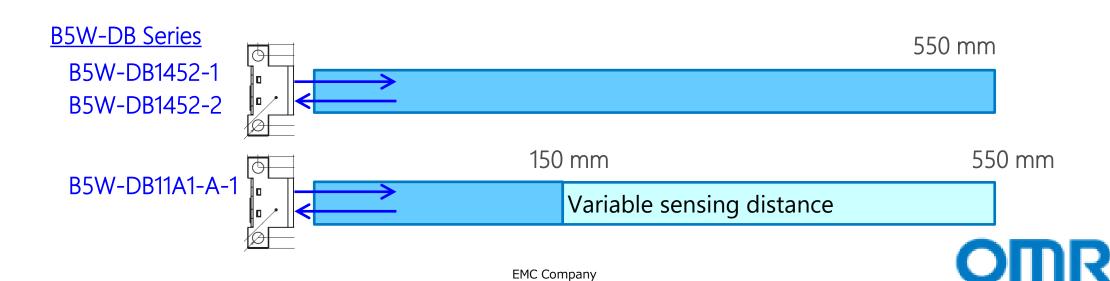






## **Background of Development**





## LDR vs LCR

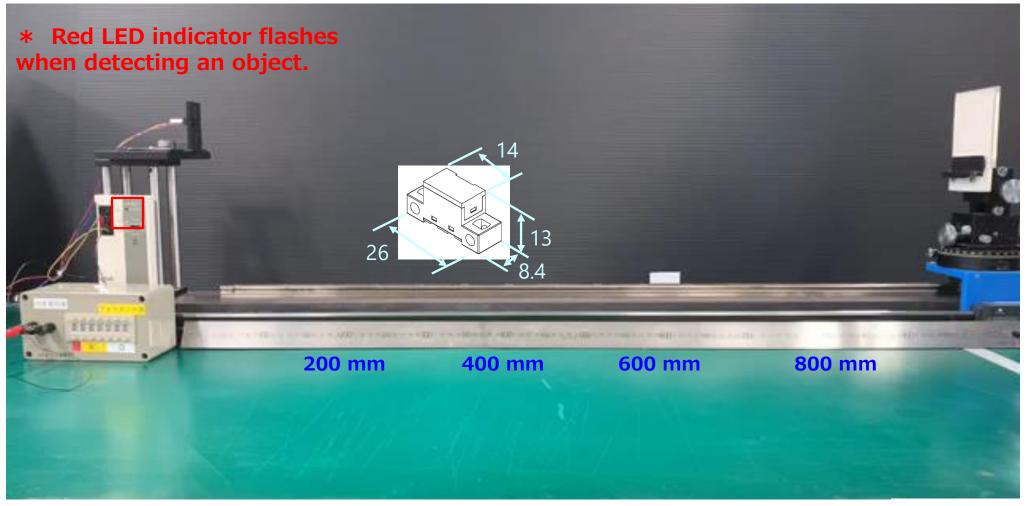
	Diffuse reflective sensor	Light convergent sensor		
Optical system	A sensor emits the light to front and the sensing area is in pink.	Sensing area is limited in pink.		
	Sensing area	<light convergent="" reflective="" type=""> Sensing area</light>		

This info is from <a href="https://omronfs.omron.com/en\_US/ecb/products/pdf/en-b5w">https://omronfs.omron.com/en\_US/ecb/products/pdf/en-b5w</a> lb series users manual.pdf



## Features of B5W-DB1452-1

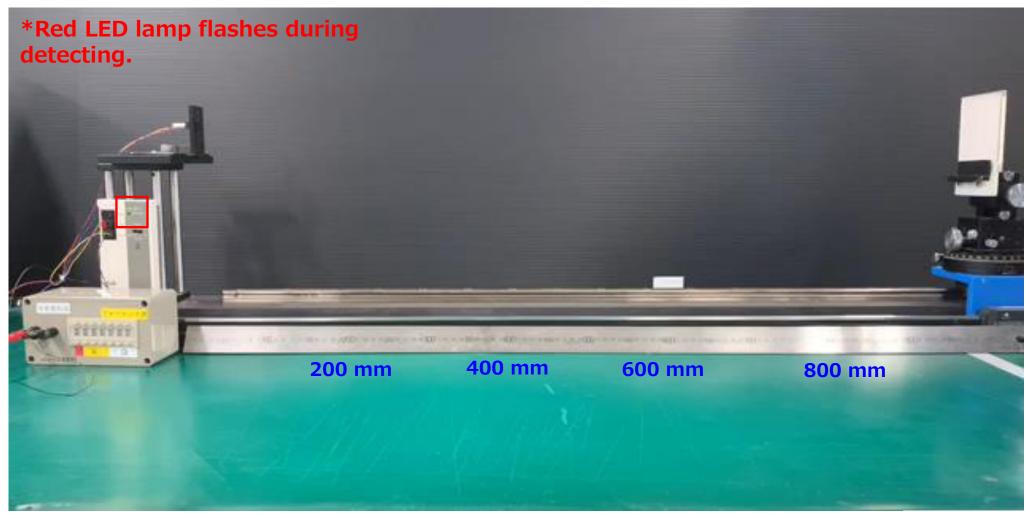
- Small-sized and long sensing distance
  - Despite the equivalent size to B5W-LB1112-1, the sensing distance of B5W-DB1452-1 is 862 mm as the average reference value, and 550 mm of guaranteed sensing distance.





## Features of B5W-DB11A1-A-1

When 0  $\Omega$ , 100  $\Omega$ , 680  $\Omega$ , 5100  $\Omega$  of external limiting resistance value (R2) is applied, the sensing distance changes to 775 mm, 615 mm, 345 mm, 125 mm, accordingly.

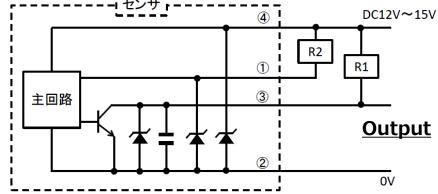




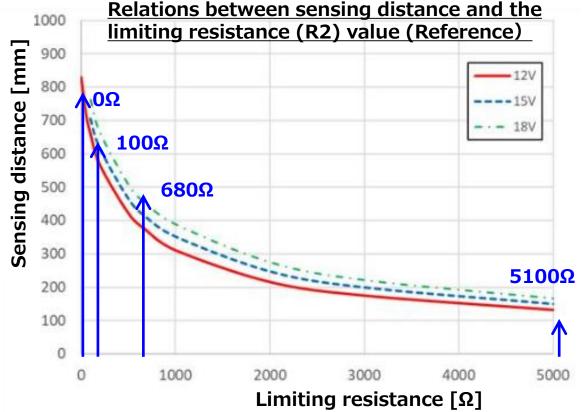
## Features of B5W-DB11A1-A-1

- Possible to change the sensing distance between 150 mm to 550 mm.
- When the external limiting resistance (R2) value increases, the current applied to LED decreases; consequently, the sensing distance becomes short. On the other hand, when the R2 value decreases, the current applied to LED increases; consequently, the sensing distance becomes long.

# Output Circuit



<sup>\*</sup>DC 18V is, as a reference, applied in demonstration with E39-VA.



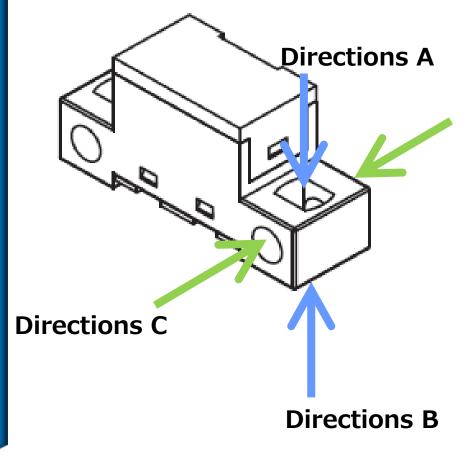
Object: White paper



<sup>\*</sup>Power Supply Voltage of B5W-DB11A1-A-1 is 12VDC/15VDC. 18VDC is out of specification.

## Mounting method

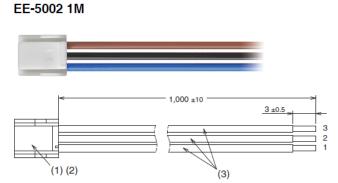
Mounted in M3 screws from 4 directions



## **Directions D**

EE-5002 is a connector with cable on sale suitable for B5W-DB series and separately ordered.

## Connector with cable (Order Separately)



No.	Name	Model/ Specifications	Quantity	Manufacturer
(1)	Connector, HS for 101-150 harness	GHR-03V-S	1	JST
(2)	Connector, CT for 101-150 harness	SSHL-002TP0.2	3	JST
(3)	Lead wires	UL1061 AWG26	3	_

#### Wiring

Connector circuit number	Lead-wire color	
1	Blue	
2	Black	
3	Brown	

## **OMRON Electronic Components Product Lineup**

## Relays

## **Switches**

## Connectors

## **Sensors & Components**

#### PCB Power Relays



Surface Mount Detection Signal Relays



Surface Mount Detection **High-frequency Relays** 



Solid-state Relays



General-purpose Relays



DC Power Relays



Power Latching Relays



Automotive Relays





Surface Mount **Detection Switches** 



General-purpose **Basic Switches** 



Sealed Ultra-subminiature **Basic Switches** 



**Pushbutton Switches** 



**Rocker Switches** 



Thumbwheel Rotary Switches





**MIL Flat Cable Connectors** 



Simple Connectors for Industrial Equipment



**FPC Connectors** 







**OKAO Vision** Image Sensing



**Human Vision Components** 



**MEMS Flow Sensors** 



**Photomicrosensors** 

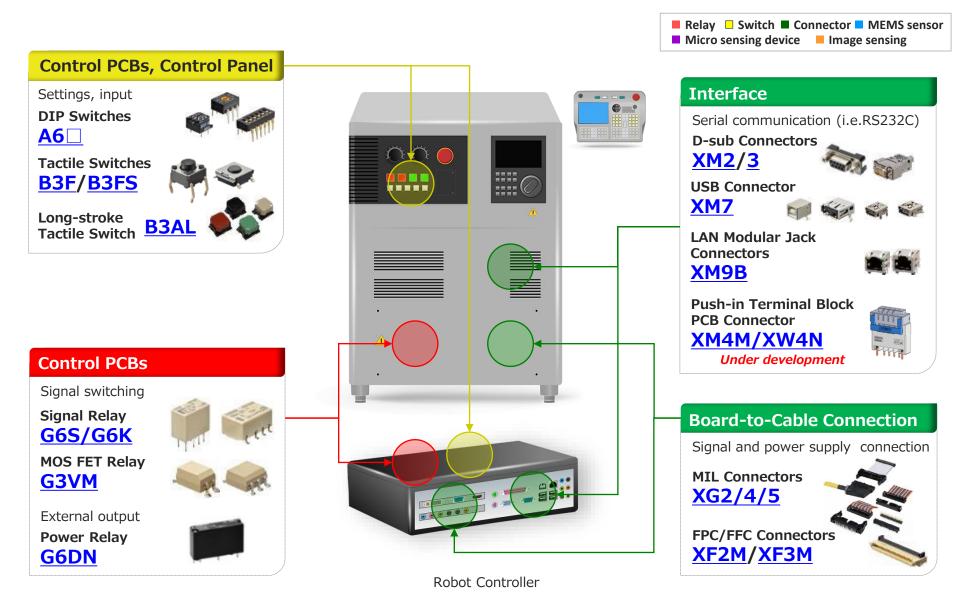


Sensors and Units designed to meet various needs in the industry



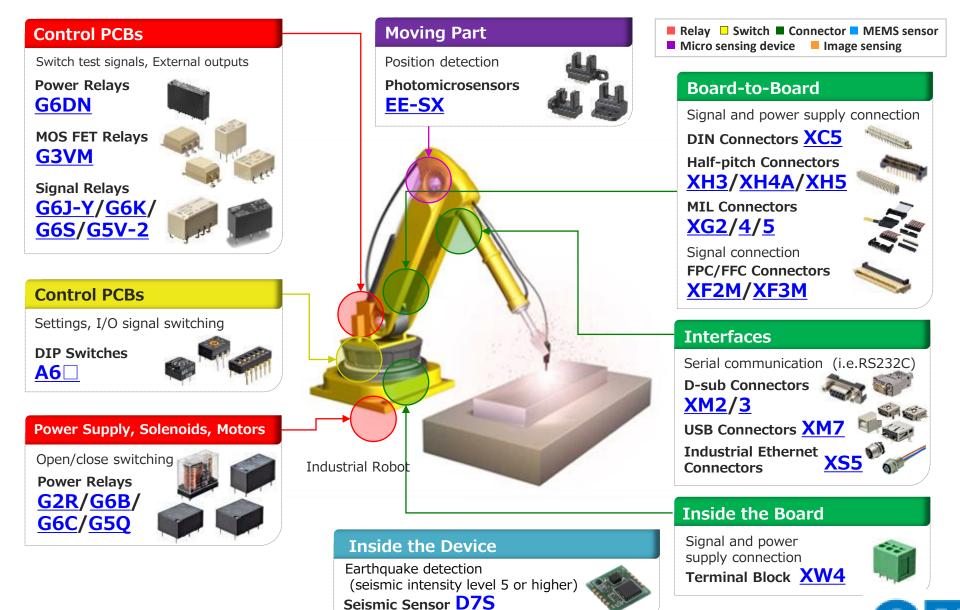


## Omron products for Robot controller





## Omron products for Industrial Robot





# Omron products for manufacturing site

